Support Vector Machines

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- Recall Decision Trees
	- Use the features in order to make recursively decisions
	- End up with a classification

- Decision trees are a type of supervised learning
	- Limited by using only a single feature

- KNN *k* nearest neighbors
	- Supervised learning
		- to classify a feature point:
			- we look at all elements in the training set
	- Drawback: Not scalable if training set is large

- SVM:
	- Uses *any* hyperplane to separate sets

- SVM:
	- Can encode the hyper-plane using a few data points:

- SVM:
	- Can solve classification even if the data set is not linearly separable

- Use a (non-linear transform of the data)
	- Kernel function: $(x, y) \mapsto (x, (x 2)^2 + (y 2)^2)$

Mathematics of SVM

- Hyper-plane through the origin is an $n 1$ -dimensional subspace of \mathbb{R}^n
	- $H = \{ \mathbf{x} \in \mathbb{R}^n | \mathbf{c} \cdot \mathbf{x} = 0 \}$
	- c is a "normal" vector, usually of length 1
	- Dot is the dot product
	- Can also use the matrix product
		- $H = \{ \mathbf{x} \in \mathbb{R}^n | \mathbf{c}^t \cdot \mathbf{x} \}$

- Task: Find *H***c**,**^p**
	- Orthogonal to vector **c**
	- Passing through a point **p**

- $\mathbf{x} \in H_{\mathbf{c},\mathbf{p}}$
	- if and only if $(x p)$ is orthogonal to c

$$
\bullet \ (\mathbf{x} - \mathbf{p}) \cdot \mathbf{c} = 0
$$

• Hyperplane given by

•
$$
H_{\mathbf{c},\mathbf{p}} = \{ \mathbf{x} \in \mathbb{R}^n | \mathbf{x} \cdot \mathbf{c} - \mathbf{c} \cdot \mathbf{p} = 0 \}
$$

$$
\bullet \qquad = \{ \mathbf{x} \in \mathbb{R}^n | \mathbf{x} \cdot \mathbf{c} + b = 0 \}
$$

• Defined by a linear functional $\lambda : \mathbb{R}^n \longrightarrow \mathbb{R}$

•
$$
H_{c,p} = \{ (\mathbf{x} \in \mathbb{R}^n | \lambda(\mathbf{x}) = b \}
$$

- Hyperplane separates space into two halves:
	- $H_{c,p}^- = \{ (x \in \mathbb{R}^n | \lambda(x) + b < 0 \}$
	- $H_{c,p}^+ = \{ (\mathbf{x} \in \mathbb{R}^n | \lambda(\mathbf{x}) + b > 0 \}$

- Learning task:
	- Find a hyperplane such that
		- All feature vectors of one category are in *H*[−] **c**,**p**
		- All feature vectors of the other category are in $H_{\mathbf{c},\mathbf{p}}^+$
	- The best hyperplane
		- (and most likely to achieve good results)
	- Maximizes distance of feature vectors from the plane

- How do we determine the distance of a point from the hyper-plane?
	- Distance is length of a line between point and closest point on the hyperplane
	- This line needs to be orthogonal to the hyperplane
		- (Otherwise can find something closer

Distance of a point from a hyperplane is the length of a normal of the hyperplane through the point.

- Let **x** be a point on the hyperplane
- Hyperplane defined by $H_{\mathbf{w},b} = \{(\mathbf{x} \in \mathbb{R}^n | \mathbf{w} \cdot \mathbf{x} + b = 0\}$
- Write
	- $\mathbf{x} \mathbf{p} = \alpha \mathbf{w} + \beta \mathbf{v}$, with $\mathbf{w} \cdot \mathbf{v} = 0$
- Multiply with **w**

•
$$
\mathbf{w} \cdot (\mathbf{x} - \mathbf{p}) = \alpha \mathbf{w} \cdot \mathbf{w} + \beta \mathbf{w} \cdot \mathbf{v} = \alpha
$$
 since
\n $\mathbf{w} \cdot \mathbf{w} = |\mathbf{w}|^2 = 1$

- Therefore
	- Projection of $\mathbf{x} \mathbf{p}$ on normal \mathbf{w} is $\mathbf{w} \cdot (\mathbf{x} \mathbf{p})$.
- This is the distance between p and the hyperplane:

$$
dist(\mathbf{p}, H_{\mathbf{w},b}) = |\alpha| = |\mathbf{w} \cdot (\mathbf{x} - \mathbf{p})|
$$

= $|\mathbf{w} \cdot \mathbf{x} - \mathbf{w} \cdot \mathbf{p}| = |-b - \mathbf{w} \cdot \mathbf{p}| = |b + \mathbf{w} \cdot \mathbf{p}|$

- Summary:
	- Want all the feature vectors of first category in

•
$$
H_{\mathbf{w},b}^- = \{ (\mathbf{x} \in \mathbb{R}^n | \mathbf{w} \cdot \mathbf{x} + b < 0 \}
$$

• Want all the feature vectors of the second category in

•
$$
H^+_{w,b} = \{ (\mathbf{x} \in \mathbb{R}^n | \mathbf{w} \cdot \mathbf{x} + b > 0 \}
$$

- First category gets label -1 , second category gets label +1
- Condition becomes:
	- $\text{label}(\mathbf{x}_i)(\mathbf{w} \cdot \mathbf{x}_i + b) > 0$
- In addition:
	- $\min_{i \in I} {\{\mathsf{label}(\mathbf{x}_i)(\mathbf{w} \cdot \mathbf{x}_i + b)\} \rightarrow \max}$ *i*∈*I*
		- where we maximize over all normals w of length 1 and all scalars *b*
- All data points $\{x_i | i \in I\}$ contribute to the optimization

- Allow normals to have length other than 1
- Replace b with $|\mathbf{w}|$ b
- Optimization becomes

$$
\bullet \qquad \min_{i \in I} \{ \text{label}(\mathbf{x}_i)(\mathbf{w} \cdot \mathbf{x}_i + b) / ||\mathbf{w}|| \} \rightarrow \max
$$

• The points \mathbf{x}_i where the minima are attained are called the support vectors.

• This even works if the two categories are **not** linearly separable

$$
\underset{i \in I}{\bullet} \text{Problem: } \min \{ \frac{\text{label}(\mathbf{x}_i)(\mathbf{w} \cdot \mathbf{x}_i + b)}{|\mathbf{w}|} \} \to \max
$$

- Support vectors: $label(\mathbf{x}) (\mathbf{w} \cdot \mathbf{x} + b) / |\mathbf{w}|$ is minimum
- Can multiply w and b with a scalar
	- Set scalar to $s = (\text{label}(\mathbf{x})(\mathbf{w} \cdot \mathbf{x} + b))^{-1}$
- Then:
	- $(\text{label}(\mathbf{x})(\mathbf{w}\cdot\mathbf{x}+b))=1$
	- Distance of **x** to hyperplane is $1/|\mathbf{w}|$
- All other feature vectors: $label(\mathbf{x}) (\mathbf{w} \cdot \mathbf{x} + b) \geq 1$

• Can now reformulate optimization problem

$$
\min_{\mathbf{w},b} \{ \frac{|\mathbf{w}|^2}{2} \} \to \min
$$

subject to

 $\forall i \in I : \text{label}(\mathbf{x}_i)(\mathbf{w}\mathbf{x}_i + b) \geq 1$

- Solve with Lagrange multiplier, traditionally called *α*
	- Solve subject to constraints

•
$$
\forall i \in I : \alpha_i(\text{label}(\mathbf{x}_i)(\mathbf{w}\mathbf{x}_i + b) - 1) = 0, \alpha_i \ge 0.
$$

\n• $L = \frac{|\mathbf{w}|^2}{2} - \sum_{i \in I} \alpha_i(\text{label}(\mathbf{x}_i)(\mathbf{w}\mathbf{x}_i + b) - 1) \rightarrow \min$

• Take partial derivatives with respect to w and b

Since
$$
\frac{\delta}{\delta w_i} \left(\frac{1}{2} \sum_{i=1}^n w_i^2 \right) = w_i
$$

• We obtain

•

•

$$
\frac{\delta}{\delta \mathbf{w}} L = \mathbf{w} - \sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i) \mathbf{x}_i
$$

$$
\frac{\delta}{\delta b} L = \sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i)
$$

• Setting them to zero for the minimum, we get

•

$$
\mathbf{w} = \sum_{i=1}^{n} \alpha_i |\text{abel}(\mathbf{x}_i)\mathbf{x}_i|
$$

and therefore

$$
\mathbf{w} = \sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i) \mathbf{x}_i
$$

$$
\bullet \quad \mathbf{w} = \sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i) \mathbf{x}_i \text{ implies}
$$

• **w** is a linear combination of features

• Use
$$
\frac{|\mathbf{w}|^2}{2} = \frac{\mathbf{w} \cdot \mathbf{w}}{2}
$$
 in our optimization problem
•
$$
L = \frac{|\mathbf{w}|^2}{2} - \sum_{i \in I} \alpha_i (\text{label}(\mathbf{x}_i)(\mathbf{w}\mathbf{x}_i + b) - 1) \rightarrow \text{min}
$$

• Use

$$
-\sum_{i\in I} \alpha_i (\text{label}(\mathbf{x}_i)(\mathbf{w}\mathbf{x}_i + b) - 1)
$$

$$
= -\mathbf{w} \cdot (\sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i)) - \sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i)b + \sum_{i=1}^{n} \alpha_i
$$

$$
= -\mathbf{w} \cdot \mathbf{w} + \sum_{i=1}^{n} \alpha_i
$$

• Function L is now simplified:

$$
L = -\frac{1}{2}\mathbf{w} \cdot \mathbf{w} + \sum_{i=1}^{n} \alpha_i
$$

• Plugging in again

$$
\bullet \quad \mathbf{W} = \sum_{i=1}^{n} \alpha_i \text{label}(\mathbf{x}_i) \mathbf{x}_i
$$

• we obtain

$$
\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_i \alpha_j
$$
label
$$
\mathbf{x}_i \cdot \mathbf{x}_j
$$

• which we want to maximize subject to constraints

$$
\forall i \in I : \alpha_i \ge 0 \text{ and } \sum_{i=1}^n \alpha_i \text{label}(\mathbf{x}_i) = 0
$$

- This is the "dual" optimization problem, but it is *quadratic* in the alphas.
	- This means that it can be solved using Kuhn Tucker

Mathematics: Soft Margin **SVM**

- The preceding works if the data set is linearly separable
	- If not, we introduce slack variables
		- $\text{label}(\mathbf{x}_i)(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1 \xi_i$
	- They measure the violation of the separation condition
		- If zero: separation condition is fulfilled and the point lies ≥ —— away from the hyperplane 1 |**w**|
		- If $0 < \xi_i < 1$: point lies inside the margin, but point is classified
		- If $\xi_i \geq 1$, point is mis-classified

- Choosing an optimization function is no longer straightforward
	- Do we want a hyperplane with a few violations or do we want to minimize the total amount of violations

• One possibility:

$$
\bullet \quad \min_{\mathbf{w},b,\xi_i} \left(\frac{|\mathbf{w}|^2}{2} + C \sum_{i=1}^n \xi_i^k \right)
$$

- subject to
- $\forall i \in I: \text{ label}(\mathbf{x}_i)(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1 \xi_i$
- $\forall i \in I: \xi_i \geq 0$

• The power *k* in

$$
\min_{\mathbf{w},b,\xi_i} \left(\frac{|\mathbf{w}|^2}{2} + C \sum_{i=1}^n \xi_i^k \right)
$$

- describes our policy:
	- *k=*1: Hinge loss
	- *k=*2: Quadratic losss
- *^C* describes the trade-off between large margins and loss minimization

- Much research has been spent on optimizing for each case
- Luckily, we do not have to use them

- Has a whole module sym
- from sklearn import svm

• Generate data

```
d_a = np.random.multivariate_normal( 
          mean = [1, 3],cov = [ [.1, .02], [ .02, .1] ], size=100) 
d b = np.random.multiparticle normal(mean = [3, 4],cov = [ [.2, .005], [ .005, .2] ], size=100)
```
• Data are the feature, target are the labels

data = np.concatenate((d a , d b), axis=0) target = $np.concatenate((np.zeros(100), np.ones(100))$

• Now fit the whole data set

```
clf = svm. SVC (kernel='linear', C=3)
clf.fit(data, target)
```
- Now print stuff:
	- To see the coefficient, we needed to use the linear kernel

```
print(clf.support_vectors_) 
w = clf.coef [0]a = -w[0] / w[1]xx = np.linspace(1.5, 2.25)yy = a * xx - (clf.intercept [0]) / w[1]
print('w',w) 
print(a)
```
• Support vectors

[[1.83311697 3.13576805] [1.49922547 3.41011599] [1.80136907 3.32299734] [2.10066171 3.82740692] [2.16113553 3.35389843] [2.48658474 2.79743539]]

• Normal and intercept:

w [2.63976203 0.98909858] -2.6688563564106373

• Draw the data and the hyperplane

```
plt.figure(1) 
plt.plot(d a[:,0], d a[:,1], 'b.')
plt.plot(d b[:,0], d b[:,1], 'r.')
plt.plot(xx, yy, 'k:') 
plt.show()
```


- New points are evaluated only using the support vectors
	- This makes SVM more efficient

• Example with non-separable data sets

• In this case, the C-value does not change much

• This is a very difficult set to classify without transformation

- If we try with several kernels, results are not so good
	- Import some stuff

```
import numpy as np 
import matplotlib.pyplot as plt 
from sklearn import svm 
from sklearn import metrics 
from sklearn.model selection import train test split
np.random.seed(12)
```
• Generate data set

$$
d_a = np.random.multivariate_normal(\n mean = [2,2],\n cov = [[.2, .15], [.15, .2]],\n size=150)\n\n d_b = np.random.multivariate_normal(\n mean = [2,2],\n cov = [[3,1], [1,3]],\n size=220)
$$

one = np.array([x for x in d_b if np.linalg.norm(x-[2,2])<1.5]) two = np.array([x for x in d_b if np.linalg.norm(x-[2,2])>2])

• Split dataset into training and test set (70% training)

```
X train, X test, y train, y test =
    train test split (
              data, 
              target, 
              test_size=0.3)
```
• Train

clf = svm.SVC(kernel = 'sigmoid') clf.fit(X train, y train)

• Predict and get accuracy:

```
y pred = clf.predict(X test)
```

```
print("Accuracy:", 
        metrics.accuracy_score(y_test, y_pred))
```
Accuracy: linear 0.62 Accuracy: poly 0.7666666666666667 Accuracy: rbf 1.0 Accuracy: sigmoid 0.34

• Could use a custom kernel

def my kernel(X, Y): return np.dot((X-[2,2])**2,((Y-[2,2])**2).T)

clf = svm.SVC(kernel = my_kernel) clf.fit(X train, y train)

• Not surprisingly, this works completely

Accuracy: 1.0

• Radial basis function kernel

$$
K(\mathbf{x}, \mathbf{y}) = \exp\left(-\frac{||\mathbf{x} - \mathbf{y}||^2}{2\sigma^2}\right)
$$